

Inline Models (LMI)

| ITEM | PART NO. OR Config. Code | DESCRIPTION | QTY | | | | |
|--------------|-----------------------------|-------------------------------------|-----|--|--|--|--|
| 3 1. | CONFIGURED | MOTOR FASTENER | 4 | | | | |
| 3 2. | CONFIGURED | MOTOR COUPLER HALF | 1 | | | | |
| 3 3. | CONFIGURED | SPIDER | 1 | | | | |
| 3 4. | CONFIGURED | ACTUATOR COUPLER HALF | | | | | |
| 3 5. | CONFIGURED | MOTOR SPACER | 1 | | | | |
| 3 6. | CONFIGURED | MOTOR SPACER FASTENER | | | | | |
| 3 7. | CONFIGURED | MOTOR SPACER COVER | 1 | | | | |
| 8. | 1906-1022 | COVER CLAMP | 1 | | | | |
| 9. | 1124-1159 | COVER FASTENER | 1 | | | | |
| 10. | 1930-1024 | DOWEL PIN | 2 | | | | |
| 11. | 1124-1082 | SPHERICAL LOCK NUT | | | | | |
| 12. | 1124-1092 | SPHERICAL WASHER | | | | | |
| 13. | 2100-1010 | RETAINING RING | | | | | |
| 14. | 3420-1222 | BEARING | | | | | |
| 1 15. | 1124-1044 | LEADSCREW SLEEVE | | | | | |
| 16. | 2212-1095 | BEARING PLATE FASTENER | | | | | |
| 17. | 1124-1037 | BEARING PLATE (US CONV.) | 1 | | | | |
| | 2124-1037 | BEARING PLATE (METRIC) | 1 | | | | |
| 4 18. | RTBRSA24 | CYLINDER BODY | 1 | | | | |
| 19. | 2224-1010 | GUIDE ROD FASTENER (US CONV.) | 2 | | | | |
| | 3224-1010 | GUIDE ROD FASTENER (METRIC) | 2 | | | | |
| | 2224-1060 | TOOLING PLATE STANDARD ROD | 2 | | | | |
| 20. | 2224-1061 | TOOLING PLATE OVERSIZE ROD | 2 | | | | |
| 20. | 3224-1060 | TOOLING PLATE STANDARD ROD (METRIC) | 2 | | | | |
| | 3224-1061 | TOOLING PLATE OVERSIZE ROD (METRIC) | 2 | | | | |

| ITEM | PART NO. OR CONFIG. CODE | DESCRIPTION | QTY | |
|------------------|--------------------------------------|----------------------------|-----|--|
| 21. | CONFIGURED | GUIDE ROD | 1 | |
| 22. | 2224-1007 | RETAINING RING | 4 | |
| | 2324-1011 | LINEAR BEARING | 1 | |
| 23. | 2224-1009 | COMPOSITE BEARING STANDARD | 1 | |
| | 2224-1012 | COMPOSITE BEARING OVERSIZE | 1 | |
| 24. | 2120-1030 | WIPER RING | 1 | |
| 25. | 2224-1005 | WICK STANDARD ROD | 2 | |
| 20. | 2224-1006 | WICK OVERSIZE ROD | 2 | |
| 26. | 2224-1001 | HOUSING (US CONV.) | 1 | |
| 20. | 3224-1001 | HOUSING (METRIC) | 1 | |
| 27. | 7. 2224-1019 MAGNET ROD | | 4 | |
| 28. | 2224-1024 | LEADSCREW FRONT BUSHING | 1 | |
| 29. | | | 1 | |
| | 0515-1076 | BN02 BALLNUT | 1 | |
| 30. | 0915-1276 | BN05 BALLNUT | 1 | |
| | 2224-9008 | BZ10 BRONZE NUT | 1 | |
| 1,3,4 31. | 31. RLSGSA24 LEADSCREW | | 1 | |
| 3 32. | TRAGSA24 | THRUST ROD | 1 | |
| 33. | 33. 2232-1011 GUIDE HOUSING FASTENER | | | |

¹ Not backward compatible with units manufactured before 01/01/2003

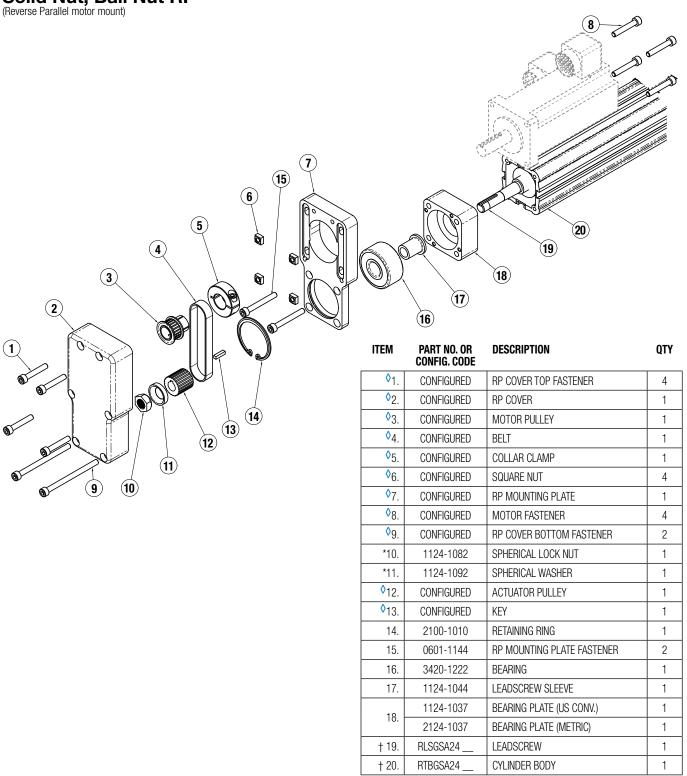
4 Replacement ordering method: RLS GSA24 ___ EXAMPLE: RILIS GISIA 24 SIN 0 1 Replacement Lead Screw -Motor Code Nut Style & Size Stroke Length Model & Size

Toll Free: 1-800-328-2174

² Not backward compatible with units manufactured before 03/01/2003

³ Part number varies depending on YMH (Your Motor Here). Contact help@tolomatic.com for replacement part number.

Solid Nut, Ball Nut RP



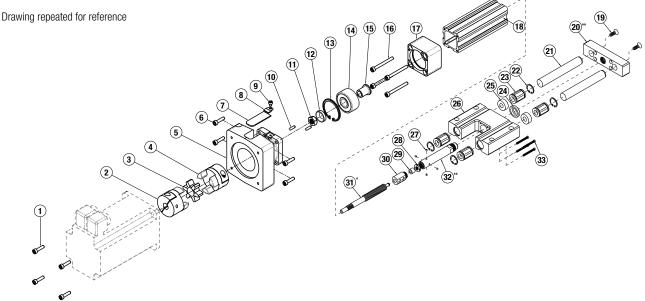
^{*}These parts are not compatible with actuators manufactured before January 2003.

† Replacement ordering method: RIS GSA24 SKU YM

EXAMPLE: RIS GSA24 SN01 SK21 25 YM

Replacement Lead Screw Nut Style & Size Stroke Length Motor Code

Part number varies depending on YMH (Your Motor Here). Contact help@tolomatic.com for replacement part number.



General Cylinder Disassembly Instructions

Begin with a clean work area. Be sure all replacement parts are present and have no visual damage or defects. The following tools are recommended for proper disassembly and assembly.

- Allen wrench set (metric)
- Socket wrench & socket set
- · Retaining ring pliers (internal & external)
- LMI Unit, Remove motor and motor spacer: Loosen the coupler screw closest to the actuator. Remove four Motor Spacer Fasteners (6) that hold the motor spacer onto actuator body. Remove the motor spacer/motor assembly.

RP, Solid Nut/Ball Nut: (Note: Reference parts list from page 2 whenever instructions refer to RP with Solid Nut/Ball Nut.) Disassemble the RP [Reverse Parallel] assembly in the following order:

- 1) Loosen the Motor Mount Fasteners (8) to remove belt tension.
- 2) Remove RP Cover (2) by removing the six Socket Head Cap Screws (1,9).
- 3) Remove Belt (4).
- 4) Remove the motor by removing the Motor Mount Fasteners (8) and the Square Nuts (6).
- 5) Remove the RP Plate (7) by removing two Socket Head Cap Screws (15). Note: the Retaining Ring (14) is part of the RP Plate. A portion of the Bearing (16) will be protruding from the Bearing Plate (18). The Bearing Plate (18) is no longer secured to the actuator body.
- 2. Remove the Tooling Plate Assembly: Using a wrench, unscrew the Thrust Rod (32) from the Tooling Plate (20). Slide the Tooling Plate (shafts still attached) out from the Housing (26).
- 3. Remove Bearing Plate/Leadscrew Assembly: Remove the four Bearing Plate Fasteners (16) that hold the Bearing Plate (17) to the actuator body. Slide the Bearing Plate, leadscrew, Thrust Rod assembly out of the Cylinder Body (18). Note: the Thrust Rod may need to be "unscrewed" from the Wiper Ring (24) in the Housing (26) in order to do this.
- Remove the Thrust Rod/Nut Assembly: Remove the Leadscrew Front Bushing (28) and Lock Nut (29) from the non-motor end of the Leadscrew.

Plastic nut style: The Leadscrew can be threaded out of the Nut (30) at this point

Ball nut style: Caution is required if removal of the Nut (30) or Leadscrew is required. Contact the factory for available parts and procedures. Note: if Ballnut (30) is removed from screw, ball bearings will fall out!

5. Remove Bearing Plate from Leadscrew: Hold the Leadscrew in a smooth

jaw vice and remove the Spherical Locknut (11). Support the Bearing Plate (17), and press the Leadscrew out of the Bearing (14)/Leadscrew Sleeve (15). The Leadscrew Sleeve (15) is a press fit in the bearing and should not be re-used. Remove the Retaining Ring (13) from Bearing Plate (17) and press the bearing out of the Bearing Plate (17).

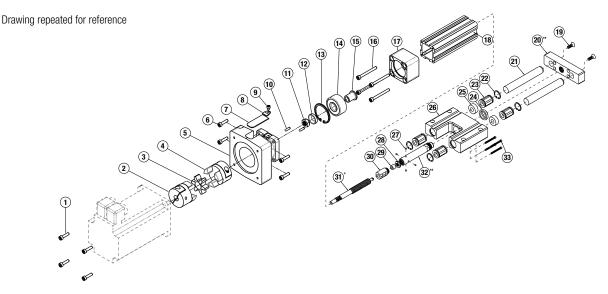
- **6. Remove the Housing from the Cylinder Body:** Remove the Guide Housing Fastener (33) from the Housing (26) to detach it from the actuator body. The Wicks (25) can be removed from the Housing (26) at this time.
- Remove the Shafts from Tooling Plate: Remove Guide Rod Fasteners (19) from Tooling Plate (20). Use a press and a tool that will fit inside the thread inside the Guide Rod (21) and press out the Guide Rods (21).
- 8. Guide Bearing & Wick removal (linear bearings only): Remove Retaining Rings (22) from the Housing (26). Slide out Linear Bearings (23). Using a screwdriver or similar tool, remove the lubrication Wicks (25). Note: the composite style of bearings are pressed in the Housing (26), they can't be removed.

General Cylinder Assembly Instructions

- 1. Install Wick and Guide Bearings (linear bearings only): Apply a light amount of oil to each Wick (25) so that they are damp. Install the wick into each groove of the Housing (26). Install four Retaining Rings (22) into the Housing (26). Rotate them such that the ball races are not aligned with each other on opposite ends of the Housing (26). Install Actuator Coupler Half (4) to hold them in place. The flat side of the ring goes against the bearing. Install Motor Spacer Fasteners (6) into groove in Housing (26). Make sure tapered edge of ring faces "out" of Housing (26).
- 2. Install bearing into Bearing Plate: Press Leadscrew Sleeve (15) into Bearing (14). Apply a coating of Loctite 641 to the ID of the Bearing Plate (17)/RP case and the OD of the Bearing (14). Locate the Bearing Plate (17)/RP Housing over the bearing and install the Retaining Ring (22).
- 3. LMI, Install Bearing onto Leadscrew: Clean ID of Leadscrew Sleeve (15) and OD of taper on Leadscrew (31). Position Bearing (14)/Leadscrew Sleeve (15) over the Leadscrew (31). Install the Spherical Washer (12) over Leadscrew (31). Apply Loctite 242 to threads of Leadscrew (31) and threads of Spherical Locknut (11). Thread on the Locknut and torque to 200 in-lbs [22.6 N-m]. Hold leadscrew in machinist vice as needed.

RP, Solid Nut/Ball Nut: (Reference parts list on page 2.) Install Leadscrew (21) into the Leadscrew Sleeve (17) and apply Loctite 242 to the threads of the Leadscrew (21). Place Key (13) onto Leadscrew (21) and install the Pulley (12), Washer (11), and Lock Nut (10) over Leadscrew (21).

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Torque Lock Nut (10) to 200 in-lbs. Hold Leadscrew (21) in machinist vice as necessary.

- 4. Install guide shafts into Tooling Plate: Press Guide Rod (21) into hole in Tooling Plate (20). The end of the shaft with the threads in it goes into the plate. Note: It is very important to press the Guide Rod (21) in straight! Use some sort of guide if possible. Repeat this for the other Guide Rod (21). Apply blue Loctite 242 to the threads of each Guide Rod Fastener (19) and thread into Guide Rods (21). Hand tighten.
- 5. Install nut, Thrust Rod onto leadscrew:

Plastic nut style: Temporarily thread the Nut (30) into Thrust Rod (32) and drill w/ 1/8th bit. Remove Nut (30) from Thrust Rod (32) and thread the Nut (30) onto the Leadscrew (31). Install the Leadscrew Front Bushing (28) and Locknut (29) on end of Leadscrew. Apply a coating of loctite 271 to the Nut (30) and thread into the Thrust Rod (32) and tighten. Install pins thru Thrust Rod (32) and into the Nut (30).

Ball nut style: Ballnut (30) is threaded into Thrust Rod (32) w/ Loctite 271.

6. Lubricate the leadscrew:

Plastic Nut: Apply a liberal film of Christo-Lube® 405 grease along the Leadscrew (31). Apply a thin film of the same grease along the ID of Thrust Rod (32).

Ballnut: Apply a liberal film of Mobilgrease® HP (Mobil blue) along the Leadscrew (31). Apply a thin film of the same grease along the ID of Thrust Rod (32).

- 7. Main actuator assembly: Locate the Cylinder Body (18) over the Thrust Rod (32)/Leadscrew assembly. Position the Housing (26) over the Thrust Rod (32). Insert the Tooling Plate (20)/Guide Rod (21) into the Housing (26). Apply loctite 242 to the thread of the Thrust Rod. Thread into the Tooling Plate (20) hand tight. With a wrench, tighten the Thrust Rod (32) _ turn. Then continue tightening until the nearest set of flats on the Thrust Rod (32) align w/ the edges of the Tooling Plate (20). This is necessary in order to align the magnets w/ the switch slots in the Cylinder Body (18). Install Guide Housing Fastener (33 thru Housing (26) and tighten. Install the Bearing Plate Fasteners (16), and tighten.
- LMI Unit, attach Motor: Attach Coupler (2,3,4) to the actuator Guide Rod (21). Attach Motor Spacer (5) to the actuator. Attach motor to the spacer and tighten down coupler fastener to motor Guide Rod (21).

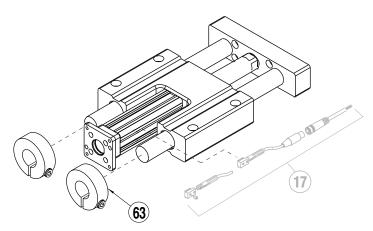
RSA24ST REVERSE PARALLEL MOTOR ASSEMBLY INSTRUCTIONS

(Note: Reference parts list from page 2 whenever instructions refer to RP with Solid Nut/Ball Nut.)

1. Align motor with slots RP Mounting Plate (7). Install four Motor Fasteners (8)

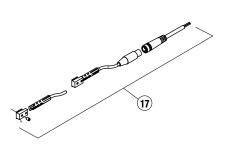
- through motor and RP Mounting Plate (7) then into the four Square Nuts (6). The Square Nuts (6) must seat into the pockets of the RP Mounting Plate (7). Tighten enough so motor is not drooping but able to move vertically.
- Align the Collar Clamp (5) with the Motor Pulley (3) and install the Motor Pulley (3) onto the motor shaft by tightening the Collar Clamp (5) fastener. Align motor pulley with the Actuator Pulley (12).
- 3. Slide Belt (4) over Motor Pulley (3) and Actuator Pulley (12).
- 4. Attach RP Motor Cover (2) to RP Motor Mounting plate (7): Solid Nut/Ball Nut: Install RP Cover (2) using two RP Cover Bottom Fasteners (9) through the RP cover, RP mounting plate, and Bearing Plate (18) and into Cylinder Body (20). Install the remaining four RP Cover Top Fasteners (1) into the RP mounting plate.
- Tension the belt following the procedures for the correct model number found listed in RP Belt Tensioning 3600-4212.

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| STOP COLLARS | | | | | | |
|--------------|-----------|---|-----|--|--|--|
| ITEM | PART # | DESCRIPTION | QTY | | | |
| 63. | 2324-1005 | STANDARD STOP COLLAR | 2 | | | |
| | 2324-1056 | STAINLESS-STEEL STOP COLLAR | 2 | | | |
| | 2332-1005 | OVERSIZE STOP COLLAR | 2 | | | |
| | 2332-1056 | OVERSIZE STAINLESS-STEEL STOP COLLAR | 2 | | | |

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To order switch kits use configuration code for switch preceded by SW and actuator code.

preceded by SW and actuator code. **EXAMPLE:** SWGSA24KK

KIT ACTUATOR SIZE SIMICH CODE WATCH CODE

The example is for a Solid State NPN, Normally Open switch with Quick-disconnect coupler. Each switch is complete with Bracket, Set Screw, Switch and mating QD cable. Note that the bracket/switch size is common and may be used on any size GSA $\,$

| ITEM | ORDER CODE | LEAD | SENSOR TYPE | SWITCHING Logic | POWER LED | SIGNAL LED | OPERATING Voltage | **POWER Rating (Watts) | SWITCHING CURRENT (MA MAX.) | CURRENT Consump- Tion | VOLTAGE DROP | LEAKAGE CURRENT | TEMP. RANGE | SHOCK / VIBRATION | |
|---|-----------------|------|----------------|----------------------------|--------------------|---------------|----------------------|------------------------------|-----------------------------------|-----------------------------|-----------------|--------------------|--|----------------------|--|
| | RY | 5M | REED | SPST NORMALLY | _ | RED | 5 - 240 AC/DC | **10.0 | 100MA | _ | 3.0 V MAX. | | | | |
| | RK | QD* | | OPEN | Tolomatio | 81009082 | | | | | | | | | |
| | NY | 5M | | | SPST NOR- MALLY | _ | YELLOW | 5 - 110 | | | | | | | |
| | NK | QD* | | CLOSED | Tolomatio | 81009084 | AC/DC | | | | | | 14 T0 158°F [-10 T0 70°C] | 50 G / 9 G | |
| | ΤY | 5M | | | GREEN | YELLOW | 10 - 30 VDC | **3.0 | 100MA | 20 MA @ 24V | 2.0 V MAX. | 0.05 MA MAX. | | | |
| 17. | 7 TK QD* | QD* | | | Tolomatio | 81009088 | | | | | | | | | |
| | KY | 5M | | | GREEN | RED | | | | | | | | | |
| | KK | QD* | SOLID STATE | | Tolomatio | 81009090 | | | | | | | | | |
| | PΥ | 5M | SOLID | | GREEN | YELLOW | | | | | | | | | |
| | PK | QD* | | ING) NORMALLY CLOSED | Tolomatio | 81009092 | | | | | | | | | |
| | HY | 5M | | NPN (SINKING) | GREEN | RED | | | | | | | | | |
| | HK | QD* | | NORMALLY CLOSED | Tolomatio | 81009094 | | | | | | | | | |
| SWITCH BRACKET, SET SCREW & MATING QD CABLE IS INCLUDED | | | | | | | | | | | | | | | |

^{*}QD = Quick-disconnect

Enclosure classification IEC 529 IP67 (NEMA 6)

CABLES: Robotic grade, oil resistant polyurethane jacket, PVC insulation

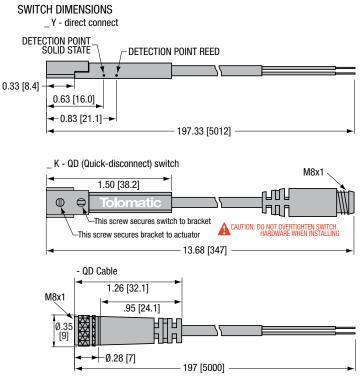
SWITCH INSTALLATION



Place switch bracket into one of the four slots that run the length of the extruded tube. Note that there is a cutout on the actuator head (RSA) or tube (GSA) to allow insertion of the bracket. Insert the switch with the word "Tolomatic" facing up and slide it under the bracket. Position the bracket with the switch to the exact location desired, then lock them securely into place by tightening both set screws on the bracket.

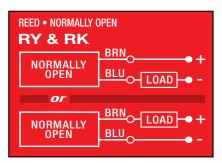
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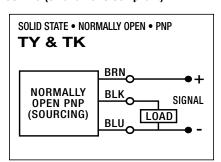
^{**}WARNING: Do not exceed power rating (Watt = Voltage x Amperage). Permanent damage to sensor will occur.

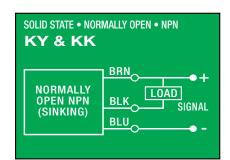


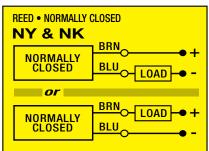
Dimensions in inches [brackets indicate dimensions in millimeters]

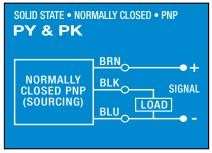
SWITCH WIRING DIAGRAMS AND LABEL COLOR CODING (CE and RoHS Compliant)

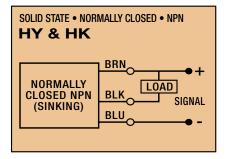


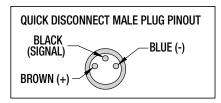


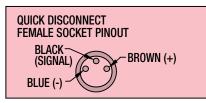












Switches:

- Include retained mounting hardware
- In slot, sit below extrusion profile
- Same for all sizes



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